

## Courses in English Course Description

<b>Department</b>	03 Mechanical, Automotive and Aeronautical Engineering
<b>Course title</b>	<b>Automotive Mechatronics II</b>
<b>Hours per week (SWS)</b>	4
<b>Number of ECTS credits</b>	5
<b>Course objective</b>	To give the student an appreciation of mechatronic systems to improve vehicular dynamics, handling and ride comfort. After taking this unit the student should be able to: <ul style="list-style-type: none"><li>- Understand the basic working principles of mechatronic systems.</li><li>- Design a mechatronic system for a given task</li><li>- Describe the system boundaries for "Driver Assistance Systems"</li><li>- Compose existing and new "Driver Assistance Systems" on the basis of mechatronic systems</li></ul>
<b>Prerequisites</b>	Informatics for Engineers
<b>Recommended reading</b>	Automobilelektronik: Eine Einführung für Ingenieure (Vieweg+Teubner) Bussysteme in der Fahrzeugtechnik: Protokolle, Standards und Softwarearchitektur (Vieweg+Teubner) Elektronik in der Fahrzeugtechnik: Hardware, Software, Systeme und Projektmanagement (Vieweg+Teubner)
<b>Teaching methods</b>	Course lecture 2 SWS, Laboratory 2 SWS
<b>Assessment methods</b>	Exam according to the legal framework of the degree program in which this course is offered. Approved aides for the examination will be published by means of the examination announcement.
<b>Language of instruction</b>	English
<b>Name of lecturer</b>	Prof. Dr. Markus Krug
<b>Email</b>	<a href="mailto:markus.krug@hm.edu">markus.krug@hm.edu</a>
<b>Link</b>	
<b>Course content</b>	Common automotive sensors and actors, driver assistance sensors (radar, lidar, ultrasonic, camera); control loop for mechatronic systems; control loop for driver assistance systems; system boundaries for driver assistance systems and legal aspects; system partitioning; functional safety judgment; functional design; developing test cases and verification techniques.
<b>Remarks</b>	Time of involvement: Presence: 45h – self-study: 105h